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# Light Sensors with Python

Exemplified by using NI USB-6008 I/O Module

Hans-Petter Halvorsen

## Free Textbook with lots of Practical Examples

## Python for Science and Engineering

Hans-Petter Halvorsen



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## **Additional Python Resources**



https://www.halvorsen.blog/documents/programming/python/

## Contents

- DAQ and I/O Modules
- NI-DAQ
- Light Sensors

Note! The Python Examples provided will work for all NI-DAQ Devices using the NI-DAQmx Driver, which is several hundreds different types. We will use the NI USB-6008 DAQ Device or I/O Module as an Example

- Light sensor, Photocell (Photo resistor),
   LDR (light-dependent resistor)
- Python Examples

## Equipment



## NI USB-6008

We will use NI USB-6008 in our examples





http://www.ni.com/en-no/support/model.usb-6008.html

## NI DAQ Device with Python

How to use a NI DAQ Device with Python



# **DAQ System**



## NI-DAQmx

- NI-DAQmx is the software you use to communicate with and control your NI data acquisition (DAQ) device.
- NI-DAQmx supports only the Windows operating system.
- Typically you use LabVIEW in combination with NI DAQ Hardware, but the NI-DAQmx can also be used from C, C#, Python, etc.
- The NI-DAQmx Driver is Free!
- Visit the <u>ni.com/downloads</u> to download the latest version of NI-DAQmx

# Measurement & Automation Explorer (MAX)

<ul> <li>W System</li> <li>J Data Neighborhood</li> <li>J Data Neighborhood</li> <li>J Devices and Interfaces</li> <li>I Network Devit"</li> <li>N USB-TCO1 "TCO1"</li> <li>N USB-TCO1 "TCO1"</li> <li>N USB-TCO1 "CO1"</li> <li>N Etwork Devices</li> <li>S Software</li> <li>Remote Systems</li> </ul>	Save concerns of the second se	Reset     Lgg vente lask     Imposed prinouts     Contigure let       Dev1     National Instruments       Ni US8-6008     03002/68       Test Panels : Ni US8-6008: "Dev1"       Analog hput     Analog Output       Digital I/O     Counter I/O		Back NI-DAQI What do y PRun the PRemov PView or	Measurement & Automation Explorer (MAX is a software you can use to configure and test the DAQ device before you use it in Python (or other programming languages).			
		Channel Name Dev J/a/0   Mode  On Demand  Irput Configuration  Differential  Min Input Linit  Min Input Linit  Min Input Linit  Samples To Read  1000  1000	Amplitude vs. Samples Chart 2.5675 - 2.5675 - 2.5665 - 2.5665 - 2.5655 - 2.5645 - 2.5645 - 2.5645 - 2.5645 - 2.5645 - 2.5645 - 2.5645 - 2.5645 - 2.5655	Aut	MAX is included with NI-DAQmx software			

With MAX you can make sure your DAQ device works as expected before you start using it in your Python program. You can use the Test Panels to test your analog and digital inputs and outputs channels.

# nidaqmx Python API

- Python Library/API for Communication with NI DAQmx Driver
- Running nidaqmx requires NI-DAQmx or NI-DAQmx Runtime
- Visit the <u>ni.com/downloads</u> to download the latest version of NI-DAQmx
- nidaqmx can be installed with pip: pip install nidaqmx
- <u>https://github.com/ni/nidaqmx-python</u>

## nidaqmx Python Package

Anaconda Prompt		_		×	Installation									
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	🔳 Anaconda Prompt					_		×						
	<pre>^ (base) C:\Users\hansha&gt;pip install nidaqmx Collecting nidaqmx Using cached https://files.pythonhosted.org/packages/c5/00/40a4ab636f91b6b3bc77e4947ffdf9ad8b4c01c1cc701b5 fc6e4df30fe34/nidaqmx-0.5.7-py2.py3-none-any.whl Requirement already satisfied: six in c:\programdata\anaconda3\lib\site-packages (from nidaqmx) (1.11.0) Requirement already satisfied: numpy in c:\programdata\anaconda3\lib\site-packages (from nidaqmx) (1.14.3) distributed 1.21.8 requires msgpack, which is not installed. Installing collected packages: nidaqmx Successfully installed nidaqmx-0.5.7 You are using pip version 10.0.1, however version 20.2.3 is available. You should consider upgrading via the 'python -m pip installupgrade pip' command. </pre>													
	(base) C: (Users (nansna)													

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# Light Sensor with Python

#### Hans-Petter Halvorsen

# Light Sensor

- Light sensor, Photocell (Photo resistor), LDR (light-dependent resistor)
- A light sensor / photocell is a sensor used to detect light.
- The resistance changes with the change in light intensity

## **Necessary Equipment**

- PC
- DAQ Module, e.g., USB-6008
- Breadboard
- Light Sensor
- Wires (Jumper Wires)
- Resistors,  $R = 10 k\Omega$



## Hardware Setup



# Voltage Divider

### The wiring is called a "Voltage Divider"



## **Python Code**

import nidaqmx

```
from nidaqmx.constants import (
    TerminalConfiguration)
```

```
value = task.read()
print(value)
```

```
task.stop
task.close()
```

## Python Code – For Loop

```
import nidaqmx
import time
from nidagmx.constants import (
    TerminalConfiguration)
task = nidaqmx.Task()
task.ai channels.add ai voltage chan("Dev1/ai0",
          terminal config=TerminalConfiguration.RSE)
task.start()
N = 60
for k in range(N):
   Vout = task.read()
   print(Vout)
   time.sleep(1)
task.stop
task.close()
```

# **Light Sensor Results**

- The resistance changes with the change in light intensity.
- We measure the the voltage (using a Voltage Divider)
- When the Light Intensity gets Higher, the Voltage Level gets Higher

**The Light Sensor has not very high accuracy**, but you can typically use it to automatically turn on a light when it get dark outside (or inside), typically used in streetlights, etc.



# Light Sensor Example

- The Light Sensor has not very high accuracy, but you can typically use it to automatically turn on a light when it get dark outside (or inside)
- In this example we will use a light sensor to measure the light intensity of the room.
  - If it's dark, we will turn on the light (LED)
  - If it's bright, we'll turn off the light (LED)

## **Necessary Equipment**

- PC
- DAQ Module, e.g., USB-6008
- Breadboard
- Light Sensor
- Wires (Jumper Wires)
- Resistors

 $\begin{array}{l} R = 270\Omega \\ R = 10k\Omega \end{array}$ 



## Hardware Setup



# Python Code

- If it's dark, we will turn on the light (LED)
- If it's bright, we'll turn off the light (LED)
- In the Example a the "Bright Level" is set to 0.2V

This value needs to be adjusted ("trial and error") depending on the use of the application.

```
import nidaqmx
import time
```

```
from nidaqmx.constants import (
    TerminalConfiguration)
```

```
task_do = nidaqmx.Task()
task_do.do_channels.add_do_chan("Dev1/port0/line0")
task_do.start()
```

```
brightlevel = 0.2
N = 60
for k in range(N):
    Vout = task_ai.read()
    print(round(Vout,2))
```

```
task_do.write(True)
```

```
if Vout < brightlevel:
    task_do.write(True)
else:
    task_do.write(False)
time.sleep(1)
```

```
task_do.write(False)
```

```
task_ai.stop; task_ai.close()
task do.stop; task do.close()
```

## **Additional Python Resources**



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